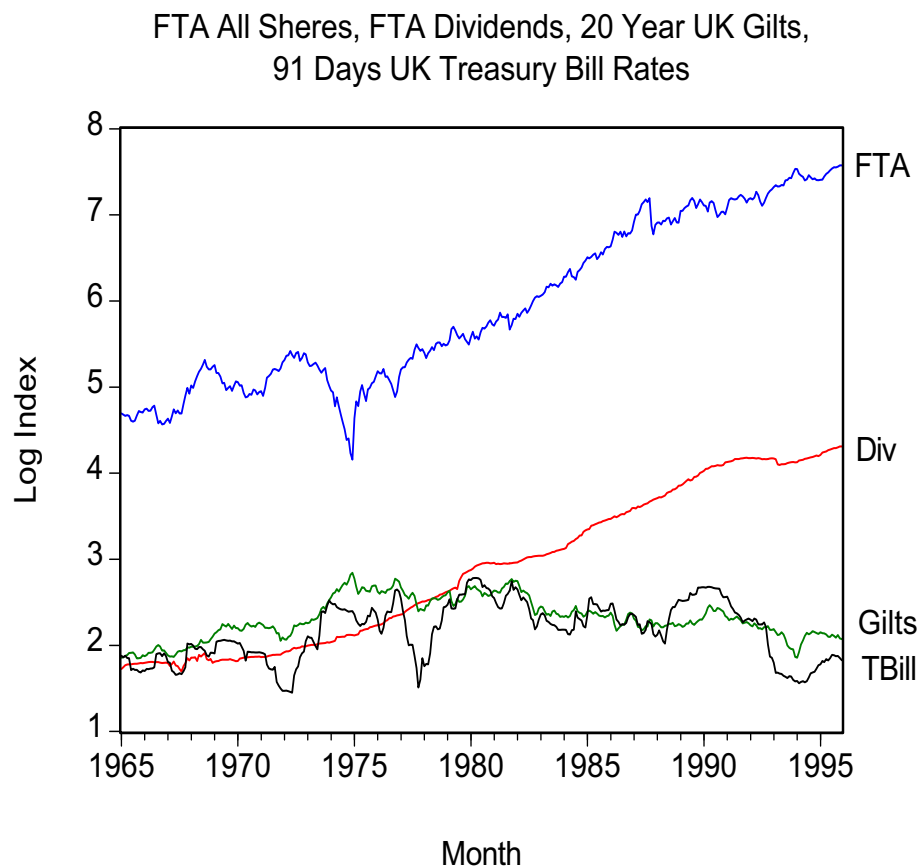


2. Multivariate Time Series

2.1 Background

Example. Consider the following monthly observations on FTA All Share index, the associated dividend index and the series of 20 year UK gilts and 91 day Treasury bills from January 1965 to December 1995 (372 months)



Potentially interesting questions:

1. Do some markets have a tendency to lead others?
2. Are there feedbacks between the markets?
3. How about contemporaneous movements?
4. How do impulses (shocks, innovations) transfer from one market to another?
5. How about common factors (disturbances, trend, yield component, risk)?

Most of these questions can be empirically investigated using tools developed in multivariate time series analysis.

Time series models

AR(p)-model

$$y_t = \mu + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \dots + \phi_p y_{t-p} + \epsilon_t$$
$$\phi(L)y_t = \mu + \epsilon_t$$

where $\epsilon_t \sim \text{WN}(0, \sigma_\epsilon^2)$ (White Noise), i.e.

$$E(\epsilon_t) = 0,$$
$$E(\epsilon_t \epsilon_s) = \begin{cases} \sigma_\epsilon^2 & \text{if } t = s \\ 0 & \text{otherwise,} \end{cases}$$

and $\phi(L) = 1 - \phi_1 L - \phi_2 L^2 - \dots - \phi_p L^p$ is the lag polynomial of order p with

$$L^k y_t = y_{t-k}$$

being the Lag operator ($L^0 y_t = y_t$).

The so called (weak) stationarity condition requires that the roots of the (characteristic) polynomial

$$\phi(L) = 0$$

should lie outside the unit circle, or equivalently the roots of

$$z^p - \phi_1 z^{p-1} - \dots - \phi_{p-1} z - \phi_p = 0$$

are less than one in absolute value.

Note. Usually the series are centralized such that $\mu = 0$.

MA(q)-model

$$\begin{aligned} y_t &= \mu + \epsilon_t + \theta_1 \epsilon_{t-1} + \dots + \theta_q \epsilon_{t-q} \\ &= \mu + \theta(L) \epsilon_t, \end{aligned}$$

where $\theta(L) = 1 + \theta_1 L + \theta_2 L^2 + \dots + \theta_q L^q$ is again a polynomial in L , this time, of order q , and $\epsilon_t \sim \text{WN}(0, \sigma_\epsilon^2)$.

Note. An MA-process is always stationary. But the so called invertibility condition requires that the roots of the characteristic polynomial $\theta(L) = 0$ lie outside the unit circle.

ARMA(p, q)-process

Compiling the two above together yields an ARMA(p, q)-process

$$\phi(L)y_t = \mu + \theta(L)\epsilon_t.$$

ARIMA(p, d, q)-process

A series is called integrated of order d , denoted as $y_t \sim I(d)$, if it becomes stationary after differencing d times. Furthermore, if

$$(1 - L)^d y_t \sim \text{ARMA}(p, q)$$

we say that $y_t \sim \text{ARIMA}(p, d, q)$, where p denotes the order of the AR-lags, q the order of MA-lags, and d the order of differencing.

Example. Univariate time series models for the above (log) series look as follows. All the series prove to be $I(1)$.

Sample: 1965:01 1995:12
Included observations: 372

FTA							
Autocorrelation	Partial Correlation		AC	PAC	Q-Stat	Prob	
*****	*****	*****	1	0.992	0.992	368.98	0.000
*****	.	.	2	0.983	-0.041	732.51	0.000
*****	.	.	3	0.975	0.021	1090.9	0.000
*****	.	.	4	0.966	-0.025	1444.0	0.000
*****	.	.	5	0.957	-0.024	1791.5	0.000
*****	.	.	6	0.949	0.008	2133.6	0.000
*****	.	.	7	0.940	0.005	2470.5	0.000
*****	.	.	8	0.931	-0.007	2802.1	0.000
*****	.	.	9	0.923	0.023	3128.8	0.000
*****	.	.	10	0.915	-0.011	3450.6	0.000

Dividends							
Autocorrelation	Partial Correlation		AC	PAC	Q-Stat	Prob	
*****	*****	*****	1	0.994	0.994	370.59	0.000
*****	.	.	2	0.988	-0.003	737.78	0.000
*****	.	.	3	0.982	0.002	1101.6	0.000
*****	.	.	4	0.976	-0.004	1462.1	0.000
*****	.	.	5	0.971	-0.008	1819.2	0.000
*****	.	.	6	0.965	-0.006	2172.9	0.000
*****	.	.	7	0.959	-0.007	2523.1	0.000
*****	.	.	8	0.953	-0.004	2869.9	0.000
*****	.	.	9	0.947	-0.006	3213.3	0.000
*****	.	.	10	0.940	-0.006	3553.2	0.000

T-Bill							
Autocorrelation	Partial Correlation		AC	PAC	Q-Stat	Prob	
*****	*****	*****	1	0.980	0.980	360.26	0.000
*****	.	.	2	0.949	-0.301	698.79	0.000
*****	.	.	3	0.916	0.020	1014.9	0.000
*****	.	.	4	0.883	-0.005	1309.5	0.000
*****	.	.	5	0.849	-0.041	1583.0	0.000
*****	.	.	6	0.811	-0.141	1833.1	0.000
*****	.	.	7	0.770	-0.018	2059.2	0.000
*****	.	.	8	0.730	0.019	2263.1	0.000
*****	.	.	9	0.694	0.058	2447.6	0.000
*****	.	.	10	0.660	-0.013	2615.0	0.000

Gilts							
Autocorrelation	Partial Correlation		AC	PAC	Q-Stat	Prob	
*****	*****	*****	1	0.984	0.984	362.91	0.000
*****	.	.	2	0.962	-0.182	710.80	0.000
*****	.	.	3	0.941	0.050	1044.6	0.000
*****	.	.	4	0.921	0.015	1365.5	0.000
*****	.	.	5	0.903	0.031	1674.8	0.000
*****	.	.	6	0.885	-0.038	1972.4	0.000
*****	.	.	7	0.866	-0.001	2258.4	0.000
*****	.	.	8	0.848	0.019	2533.6	0.000
*****	.	.	9	0.832	0.005	2798.6	0.000
*****	.	.	10	0.815	-0.014	3053.6	0.000

Formally, as is seen below, the Dickey-Fuller (DF) unit root tests indicate that the series indeed all are $I(1)$. The test is based on the augmented DF-regression

$$\Delta y_t = \rho y_{t-1} + \alpha + \delta t + \sum_{i=1}^4 \phi_i \Delta y_{t-i} + \epsilon_t,$$

and the hypothesis to be tested is

$$H_0 : \rho = 0 \text{ vs } H_1 : \rho < 0.$$

Test results:

Series	$\hat{\rho}$	t -Stat
FTA	-0.030	-2.583
DIV	-0.013	-2.602
R20	-0.013	-1.750
T-BILL	-0.023	-2.403
Δ FTA	-0.938	-8.773
Δ DIV	-0.732	-7.300
Δ R20	-0.786	-8.129
Δ T-BILL	-0.622	-7.095
ADF critical values		
Level	No trend	Trend
1%	-3.4502	-3.9869
5%	-2.8696	-3.4237
10%	-2.5711	-3.1345

Provided that the series are not *cointegrated* an appropriate modeling approach is VAR for the differences.

2.2 Vector Autoregression (VAR)

Suppose we have m time series y_{it} , $i = 1, \dots, m$, and $t = 1, \dots, T$ (common length of the time series). Then a vector autoregression model is defined as

$$\begin{pmatrix} y_{1t} \\ y_{2t} \\ \vdots \\ y_{mt} \end{pmatrix} = \begin{pmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_m \end{pmatrix} + \begin{pmatrix} \phi_{11}^{(1)} & \phi_{12}^{(1)} & \cdots & \phi_{1m}^{(1)} \\ \phi_{21}^{(1)} & \phi_{22}^{(1)} & \cdots & \phi_{2m}^{(1)} \\ \vdots & \vdots & \ddots & \vdots \\ \phi_{m1}^{(1)} & \phi_{m2}^{(1)} & \cdots & \phi_{mm}^{(1)} \end{pmatrix} \begin{pmatrix} y_{1,t-1} \\ y_{2,t-1} \\ \vdots \\ y_{m,t-1} \end{pmatrix} + \dots + \begin{pmatrix} \phi_{11}^{(p)} & \phi_{12}^{(p)} & \cdots & \phi_{1m}^{(p)} \\ \phi_{21}^{(p)} & \phi_{22}^{(p)} & \cdots & \phi_{2m}^{(p)} \\ \vdots & \vdots & \ddots & \vdots \\ \phi_{m1}^{(p)} & \phi_{m2}^{(p)} & \cdots & \phi_{mm}^{(p)} \end{pmatrix} \begin{pmatrix} y_{1,t-p} \\ y_{2,t-p} \\ \vdots \\ y_{m,t-p} \end{pmatrix} + \begin{pmatrix} \epsilon_{1t} \\ \epsilon_{2t} \\ \vdots \\ \epsilon_{mt} \end{pmatrix}.$$

In matrix notations

$$y_t = \mu + \Phi_1 y_{t-1} + \dots + \Phi_p y_{t-p} + \epsilon_t,$$

which can be further simplified by adopting the matrix form of a lag polynomial

$$\Phi(L) = \mathbf{I} - \Phi_1 L - \dots - \Phi_p L^p.$$

Thus finally we get

$$\Phi(L)\mathbf{y}_t = \boldsymbol{\epsilon}_t.$$

Note that each y_{it} does not only depend on its own history but also on the other series' history (cross dependencies). This gives us several additional tools for analyzing causal as well as feedback effects as we shall see after a while.

A basic assumption in the above model is that the residual vector follow a multivariate white noise, i.e.

$$\begin{aligned} E(\boldsymbol{\epsilon}_t) &= \mathbf{0} \\ E(\boldsymbol{\epsilon}_t \boldsymbol{\epsilon}_s') &= \begin{cases} \boldsymbol{\Sigma}_\epsilon & \text{if } t = s \\ \mathbf{0} & \text{if } t \neq s \end{cases}, \end{aligned}$$

which allows for estimation by OLS, because each individual residual series is assumed to be serially uncorrelated with constant variance.

The coefficient matrices must satisfy certain constraints in order that the VAR-model is stationary. They are just analogies with the univariate case, but in matrix terms. It is required that the roots of

$$|\mathbf{I} - \Phi_1 z - \Phi_2 z^2 - \dots - \Phi_p z^p| = 0$$

lie outside the unit circle. Estimation can be carried out by single equation least squares.

Example. Let us estimate a VAR model for the equity-bond data. First, however, test whether the series are cointegrated. As is seen below, there is no empirical evidence of cointegration (EViews results)

Sample(adjusted): 1965:06 1995:12
 Included observations: 367 after adjusting end points
 Trend assumption: Linear deterministic trend
 Series: LFTA LDIV LR20 LTBILL
 Lags interval (in first differences): 1 to 4

Unrestricted Cointegration Rank Test

```

=====
Hypothesized              Trace          5 Percent          1 Percent
No. of CE(s) Eigenvalue  Statistic  Critical Value  Critical Value
=====
None                      0.047131    46.02621      47.21          54.46
At most 1                  0.042280    28.30808      29.68          35.65
At most 2                  0.032521    12.45356      15.41          20.04
At most 3                  0.000872     0.320012      3.76           6.65
=====
  
```

*(**) denotes rejection of the hypothesis at the 5%(1%) level
 Trace test indicates no cointegration at both 5% and 1% levels

VAR(2) Estimates:

Sample(adjusted): 1965:04 1995:12

Included observations: 369 after adjusting end points

Standard errors in () & t-statistics in []

```

=====
                DFTA          DDIV          DR20          DTBILL
=====
DFTA(-1)          0.102018  -0.005389  -0.140021  -0.085696
                 (0.05407) (0.01280)  (0.02838)  (0.05338)
                 [1.88670] [-0.42107] [-4.93432] [-1.60541]
DFTA(-2)          -0.170209  0.012231  0.014714  0.057226
                 (0.05564) (0.01317)  (0.02920)  (0.05493)
                 [-3.05895] [0.92869]  [0.50389]  [1.04180]
DDIV(-1)          -0.113741  0.035924  0.197934  0.280619
                 (0.22212) (0.05257)  (0.11657)  (0.21927)
                 [-0.51208] [0.68333]  [1.69804]  [1.27978]
DDIV(-2)          0.065178  0.103395  0.057329  0.165089
                 (0.22282) (0.05274)  (0.11693)  (0.21996)
                 [0.29252] [1.96055]  [0.49026]  [0.75053]
DR20(-1)          -0.359070  -0.003130  0.282760  0.373164
                 (0.11469) (0.02714)  (0.06019)  (0.11322)
                 [-3.13084] [-0.11530] [4.69797]  [3.29596]
DR20(-2)          0.051323  -0.012058  -0.131182  -0.071333
                 (0.11295) (0.02673)  (0.05928)  (0.11151)
                 [0.45437] [-0.45102] [-2.21300] [-0.63972]
DTBILL(-1)        0.068239  0.005752  -0.033665  0.232456
                 (0.06014) (0.01423)  (0.03156)  (0.05937)
                 [1.13472] [0.40412] [-1.06672] [3.91561]
DTBILL(-2)        -0.050220  0.023590  0.034734  -0.015863
                 (0.05902) (0.01397)  (0.03098)  (0.05827)
                 [-0.85082] [1.68858]  [1.12132] [-0.27224]
C                  0.892389  0.587148  -0.033749  -0.317976
                 (0.38128) (0.09024)  (0.20010)  (0.37640)
                 [2.34049] [6.50626] [-0.16867] [-0.84479]
=====

```

Continues ...

	DFTA	DDIV	DR20	DTBILL
R-squared	0.057426	0.028885	0.156741	0.153126
Adj. R-squared	0.036480	0.007305	0.138002	0.134306
Sum sq. resids	13032.44	730.0689	3589.278	12700.62
S.E. equation	6.016746	1.424068	3.157565	5.939655
F-statistic	2.741619	1.338486	8.364390	8.136583
Log likelihood	-1181.220	-649.4805	-943.3092	-1176.462
Akaike AIC	6.451058	3.569000	5.161567	6.425267
Schwarz SC	6.546443	3.664385	5.256953	6.520652
Mean dependent	0.788687	0.688433	0.052983	-0.013968
S.D. dependent	6.129588	1.429298	3.400942	6.383798
Determinant Residual Covariance		18711.41		
Log Likelihood (d.f. adjusted)		-3909.259		
Akaike Information Criteria		21.38352		
Schwarz Criteria		21.76506		

As is seen the number of estimated parameters grows rapidly very large.

Defining the order of a VAR-model

In the first step it is assumed that all the series in the VAR model have equal lag lengths. To determine the number of lags that should be included, multivariate extensions of criterion functions like SC and AIC can be utilized in the same manner as in the univariate case.

The likelihood ratio (LR) test can also be used in determining the order of a VAR. The test is generally of the form

$$LR = T(\log |\hat{\Sigma}_k| - \log |\hat{\Sigma}_m|)$$

where $\hat{\Sigma}_k$ denotes the maximum likelihood estimate of the residual covariance matrix of VAR(k) and $\hat{\Sigma}_m$ the estimate of VAR(m) ($m > k$) residual covariance matrix. If VAR(k) (the shorter model) is the true one, then

$$LR \sim \chi_{df}^2,$$

where the degrees of freedom, df , equals the difference of in the number of estimated parameters between the two models.

In a p variate VAR(k)-model each series has $m - k$ lags less than those in VAR(m). Thus the difference in each equation is $p(m - k)$, so that in total $df = p^2(m - k)$.

Note that often, when T small a modified LR

$$LR^* = (T - pm)(\log |\hat{\Sigma}_k| - \log |\hat{\Sigma}_m|)$$

is used to correct for small sample bias.

Example Let $m = 12$ then in the equity-bond data different VAR models yield the following results. Below are EViews results.

VAR Lag Order Selection Criteria
 Endogenous variables: DFTA DDIV DR20 DTBILL
 Exogenous variables: C
 Sample: 1965:01 1995:12
 Included observations: 359

Lag	LogL	LR	FPE	AIC	SC	HQ
0	-3860.59	NA	26324.1	21.530	21.573	21.547
1	-3810.15	99.473	21728.6*	21.338*	21.554*	21.424*
2	-3796.62	26.385	22030.2	21.352	21.741	21.506
3	-3786.22	20.052	22729.9	21.383	21.945	21.606
4	-3783.57	5.0395	24489.4	21.467	22.193	21.750
5	-3775.66	14.887	25625.4	21.502	22.411	21.864
6	-3762.32	24.831	26016.8	21.517	22.598	21.947
7	-3753.94	15.400	27159.4	21.560	22.814	22.059
8	-3739.07	27.018*	27348.2	21.566	22.994	22.134
9	-3731.30	13.933	28656.4	21.612	23.213	22.248
10	-3722.40	15.774	29843.7	21.651	23.425	22.357
11	-3715.54	12.004	31443.1	21.702	23.649	22.476
12	-3707.28	14.257	32880.6	21.745	23.865	22.588

* indicates lag order selected by the criterion
 LR: sequential modified LR test statistic
 (each test at 5% level)
 FPE: Final prediction error
 AIC: Akaike information criterion
 SC: Schwarz information criterion
 HQ: Hannan-Quinn information criterion

Criterion function minima are all at VAR(1) (SC or BIC just borderline). LR-tests suggest VAR(8) based upon the first significant LR($m, m - 1$) statistics starting from $m = 12$.

Model Diagnostics

Even though the information criteria were seen to favour VAR(1), we decided to fit a VAR(2) model to the data, because the VAR(1) residuals do not pass the white noise test, as we shall see below.

To investigate whether the VAR residuals are white noise, the hypothesis to be tested is

$$H_0 : \Upsilon_1 = \dots = \Upsilon_h = 0,$$

where $\Upsilon_k = (\gamma_{ij}(k))$ denotes the matrix of the k 'th cross autocovariances of the residuals series ϵ_i and ϵ_j :

$$\gamma_{ij}(k) = E(\epsilon_{i,t-k} \cdot \epsilon_{j,t}),$$

whose diagonal elements reduce to the usual autocovariances γ_k . Note, however, that cross-autocovariances, unlike univariate autocovariances, are not symmetric in k , that is $\gamma_{i,j}(k) \neq \gamma_{i,j}(-k)$, because the covariance between residual series i and residual series j k steps ahead is in general not the same as the covariance between residual series i and the residual series j k steps before. Stationarity ensures, however, that $\Upsilon_k = \Upsilon'_{-k}$ (exercise).

In order to test $H_0 : \Upsilon_1 = \dots = \Upsilon_h = 0$, we may use the (Portmanteau) Q -statistics^{††}

$$Q_h = T \sum_{k=1}^h \text{tr}(\hat{\Upsilon}'_k \hat{\Upsilon}_0^{-1} \hat{\Upsilon}_k \hat{\Upsilon}_0^{-1})$$

where

$$\hat{\Upsilon}_k = (\hat{\gamma}_{ij}(k)) \text{ with } \hat{\gamma}_{ij}(k) = \frac{1}{T-k} \sum_{t=k}^T \hat{\epsilon}_{t-k,i} \hat{\epsilon}_{t,j}$$

are the estimated (residual) cross autocovariances and $\hat{\Upsilon}_0$ the contemporaneous covariances of the residuals. Alternatively (especially in small samples) a modified statistic is used

$$Q_h^* = T^2 \sum_{k=1}^h (T-k)^{-1} \text{tr}(\hat{\Upsilon}'_k \hat{\Upsilon}_0^{-1} \hat{\Upsilon}_k \hat{\Upsilon}_0^{-1}).$$

The statistics are asymptotically χ^2 distributed with $p^2(h-k)$ degrees of freedom. Note that in computer printouts h is running from $1, 2, \dots, h^*$ with h^* specified by the user.

^{††}See e.g. Lütkepohl, Helmut (1993). *Introduction to Multiple Time Series*, 2nd Ed., Ch. 4.4

The table below contains the Q -statistics of the VAR(1) residuals fitted to financial market data from January 1965 to December 1995.

VAR(1) Residual Portmanteau Tests for Autocorrelations

H0: no residual autocorrelations up to lag h

Sample: 1966:02 1995:12

Included observations: 359

```
=====
```

Lags	Q-Stat	Prob.	Adj Q-Stat	Prob.	df
1	1.847020	NA*	1.852179	NA*	NA*
2	27.66930	0.0346	27.81912	0.0332	16
3	44.05285	0.0761	44.34073	0.0721	32
4	53.46222	0.2725	53.85613	0.2603	48
5	72.35623	0.2215	73.01700	0.2059	64
6	96.87555	0.0964	97.95308	0.0843	80
7	110.2442	0.1518	111.5876	0.1320	96
8	137.0931	0.0538	139.0485	0.0424	112
9	152.9130	0.0659	155.2751	0.0507	128
10	168.4887	0.0797	171.2972	0.0599	144
11	179.3347	0.1407	182.4860	0.1076	160
12	189.0256	0.2379	192.5120	0.1869	176

```
=====
```

*The test is valid only for lags larger than the VAR lag order. df is degrees of freedom for (approximate) chi-square distribution

There is still left some autocorrelation in the VAR(1) residuals. Let us next check the residuals of the VAR(2) model.

VAR Residual Portmanteau Tests for Autocorrelations

H0: no residual autocorrelations up to lag h

Sample: 1965:01 1995:12

Included observations: 369

```
=====
```

Lags	Q-Stat	Prob.	Adj Q-Stat	Prob.	df
1	0.438464	NA*	0.439655	NA*	NA*
2	1.623778	NA*	1.631428	NA*	NA*
3	17.13353	0.3770	17.26832	0.3684	16
4	27.07272	0.7143	27.31642	0.7027	32
5	44.01332	0.6369	44.48973	0.6175	48
6	66.24485	0.3994	67.08872	0.3717	64
7	80.51861	0.4627	81.63849	0.4281	80
8	104.3903	0.2622	106.0392	0.2271	96
9	121.8202	0.2476	123.9049	0.2081	112
10	136.8909	0.2794	139.3953	0.2316	128
11	147.3028	0.4081	150.1271	0.3463	144
12	157.4354	0.5425	160.6003	0.4718	160

```
=====
```

*The test is valid only for lags larger than the VAR lag order.

df is degrees of freedom for (approximate) chi-square distribution

Now the residuals pass the white noise test. On the basis of these residual analyses we can select VAR(2) as the specification for further analysis. Mills (1999) finds VAR(6) as the most appropriate one. Note that there ordinary differences (opposed to log-differences) are analyzed. Here, however, log transformations are preferred.

Vector ARMA (VARMA)

Similarly as is done in the univariate case one can extend the VAR model to the vector ARMA model

$$\mathbf{y}_t = \mu + \sum_{i=1}^p \Phi_i \mathbf{y}_{t-i} + \epsilon_t + \sum_{j=1}^q \Theta_j \epsilon_{t-j}$$

or

$$\Phi(L)\mathbf{y}_t = \mu + \Theta(L)\epsilon_t,$$

where \mathbf{y}_t , μ , and ϵ_t are $m \times 1$ vectors, and Φ_i 's and Θ_j 's are $m \times m$ matrices, and

$$\begin{aligned}\Phi(L) &= \mathbf{I} - \Phi_1 L - \dots - \Phi_p L^p \\ \Theta(L) &= \mathbf{I} + \Theta_1 L + \dots + \Theta_q L^q.\end{aligned}$$

Provided that $\Theta(L)$ is invertible, we always can write the VARMA(p, q)-model as a VAR(∞) model with $\Pi(L) = \Theta^{-1}(L)\Phi(L)$. The presence of a vector MA component, however, implies that we can no longer find parameter estimates by ordinary least squares. We do not pursue our analysis to this direction.